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| <code>example_getCalibParamsFile.cc</code> | Get the internal parameters of the camera                 |
| <code>example_getDepthFrame.cc</code>      | Get camera depth video stream                             |
| <code>example_getPointCloud.cc</code>      | Get camera point cloud                                    |
| <code>example_getRawFrame.cc</code>        | Get camera RGB binocular video stream                     |
| <code>example_getRectFrame.cc</code>       | Obtain RGB binocular video stream after camera correction |